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Bat Algorithm

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Agenda

- ❑ **Algorithm Origin**
- ❑ **Bat Echolocation**
- ❑ **Simulation of bat behavior**
- ❑ **Bat Algorithm (BA)**
- ❑ **BA as an extension of PSO**
- ❑ **Variants of BA**
- ❑ **Applications**

The Algorithm Origin

- ❑ Authors: Xin-She Yang
- ❑ Title: A New Metaheuristic Bat-Inspired Algorithm,
- ❑ Publication: *Nature Inspired Cooperative Strategies for Optimization (NISCO 2010)* (Eds. J. R. Gonzalez et al.), in *Studies in Computational Intelligence*, Springer Berlin, 284, Springer, 65-74 (2010).
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How are bats fascinating?

- ❑ Bats are the only mammals that possess wings.
- ❑ There are around 1000 different species of bats, most of them are insectivore.
- ❑ They are of the order of Chiroptera.

❑ Two main Types of bats

Mega-bats

- ✓ Size: big
- ✓ Vision: well-developed
 - Visual cortices
 - Good visual acuity
- ✓ Smell sense
- ✓ No Echolocation

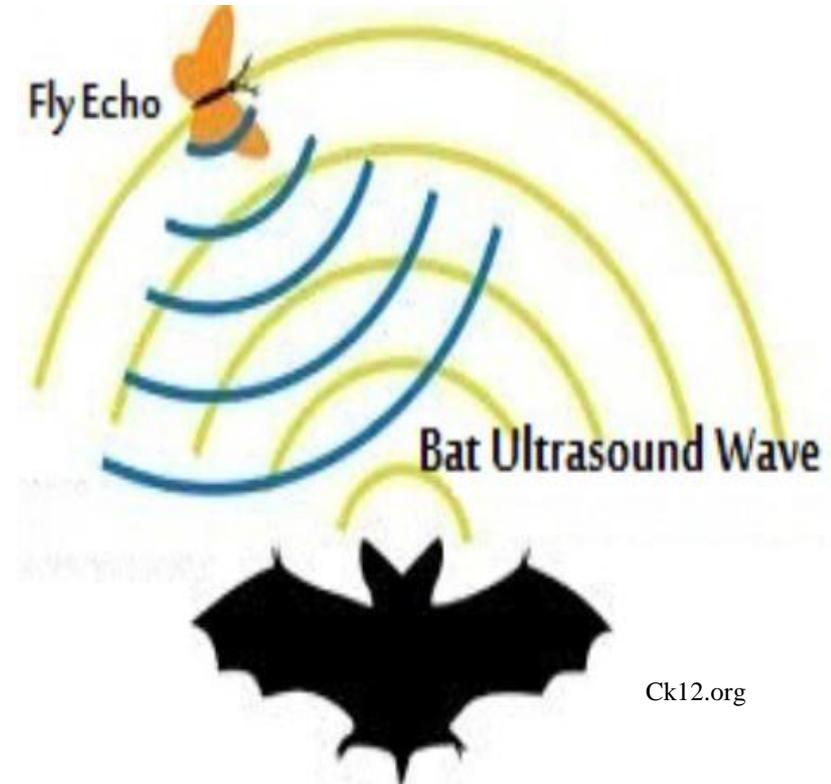
Micro-bats

- Use a sound called *Echolocation* to
- ✓ detect preys
- ✓ Avoid obstacles
- ✓ Locate the roosting crevices
- ✓ All these tasks are performed in complete darkness

Bats of intermediary size use a certain degree of echolocation.

Bat Echolocation

- ❑ Echolocation consists in producing a sonar composed of 2 steps:
 - emitting sound pulses
 - and then detecting surrounding objects from the reflected echo
- ❑ The sonar is also used under water by some kinds of fishes.
- ❑ It is also used by humans (Japanese) to attract and catch fishes.
- ❑ Micro-bats perceive their environment by:
 - Measuring the distance and orientation of the objects.
 - Detecting the type and the speed of the preys.



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Bat Echolocation phenomenon

Simulation of Bats Behavior using Echolocation

- ❑ As for all the nature and biology-inspired approaches, bat-inspired approach simulates the movement of bats when searching for preys.
- ❑ The real bats are simulated by artificial bats as follows:

The natural bats

- ❑ Environment: the nature and the roosting crevices where the bats live.
- ❑ Swarm: bats from roosting crevices
- ❑ Target: preys (insects)
- ❑ Movement: natural based on echolocation and hunting strategies
- ❑ Bats evaluation (position, velocity ...)

The artificial bats

- ❑ Search space: set of all possible solutions encapsulated in artificial bats
- ❑ Population of artificial bats or solutions
- ❑ Target: optimal solutions
- ❑ Movement: determined by mathematical equations based on simulated echolocation
- ❑ Fitness function

Approximations and Simplifications

- ❑ Bats use echolocation to sense distance and perceive in a magical way their surroundings.

- ❑ Bats fly randomly with:
 - velocity v_i
 - at position x_i
 - with a fixed frequency f_{min} ,
 - varying wavelength λ and loudness A_0 to search for prey.

- ❑ They automatically adjust the wavelength of their emitted pulses and adjust the rate of pulse emission r from $[0,1]$, depending on the proximity of their prey.

- ❑ The loudness varies from a positive large value A_0 to a minimum value A_{min} .

Bat Motion

- x' is the best solution of the current iteration.
- x^* is the best solution of all the previous iterations.
- The movement of a bat is modelled as:

$$f_i = f_{min} + (f_{max} - f_{min})\beta$$
$$v_i^t = v_i^{t-1} + (x_i^t - x_*)f_i$$
$$x_i^t = x_i^{t-1} + v_i^t$$

where β is an empirical parameter

- The best solution of one iteration is

$$x_{new} = x' + \varepsilon * A_i$$

- The update of loudness and pulse rate

$$A_i^t = \alpha A_i^{t-1}$$

$$r_i^{t+1} = r_i^0(1 - e^{\gamma t})$$

Bat Algorithm

```
begin
  generate at random a population of  $k$  bats ( $k$  solutions);
  for each bat  $i$  do
    define its loudness  $A_i$ , its pulse frequency  $f_i$  and its velocity  $v_i$ ;
    set its pulse rate to  $r_i$  ;
    select the best solution  $x^*$ ;
  while ((Max-Iter not reached) do
    for each  $i = 1$  to  $k$  do
      compute a new solution  $(f_i, v_i, x_i)$  using these formulas
      if (rand >  $r_i$ ) then
        select a solution  $x'$  among the best solutions;
        improve the solution using this formula ;
      end if;
      generate at random a new solution  $(f_i, v_i, x_i)$  ;
      if (rand <  $A_i$ ) and ( $f(x_i) < f(x^*)$ ) then
        accept the new solution;
        increase  $r_i$  and reduce  $A_i$  using these formulas end if
      end for
      Rank the bats and find the current best solution  $x^*$  ;
    end while
  end
```

$$f_i = f_{min} + (f_{max} - f_{min})\beta$$
$$v_i^t = v_i^{t-1} + (x_i^t - x_*)f_i$$
$$x_i^t = x_i^{t-1} + v_i^t$$

$$x_{new} = x' + \varepsilon * A$$

$$A_i^t = \alpha A_i^{t-1}$$

$$r_i^{t+1} = r_i^0(1 - e^{\gamma t})$$

Data structures

□ The Bats Table.

- The bats table memorizes the pulse frequency, the velocity and the position of each bat at time t (each iteration).
- Each entry corresponds to a bat for the current iteration.
- \mathbf{x}^* is the best solution found so far, by any bat in the swarm, from the beginning of the bat process. \mathbf{x}' is the best solution found at one iteration.

Bats Table

bat 1			
bat 2			
bat i			
bat k			
	f_i	v_i^t	x_i^t

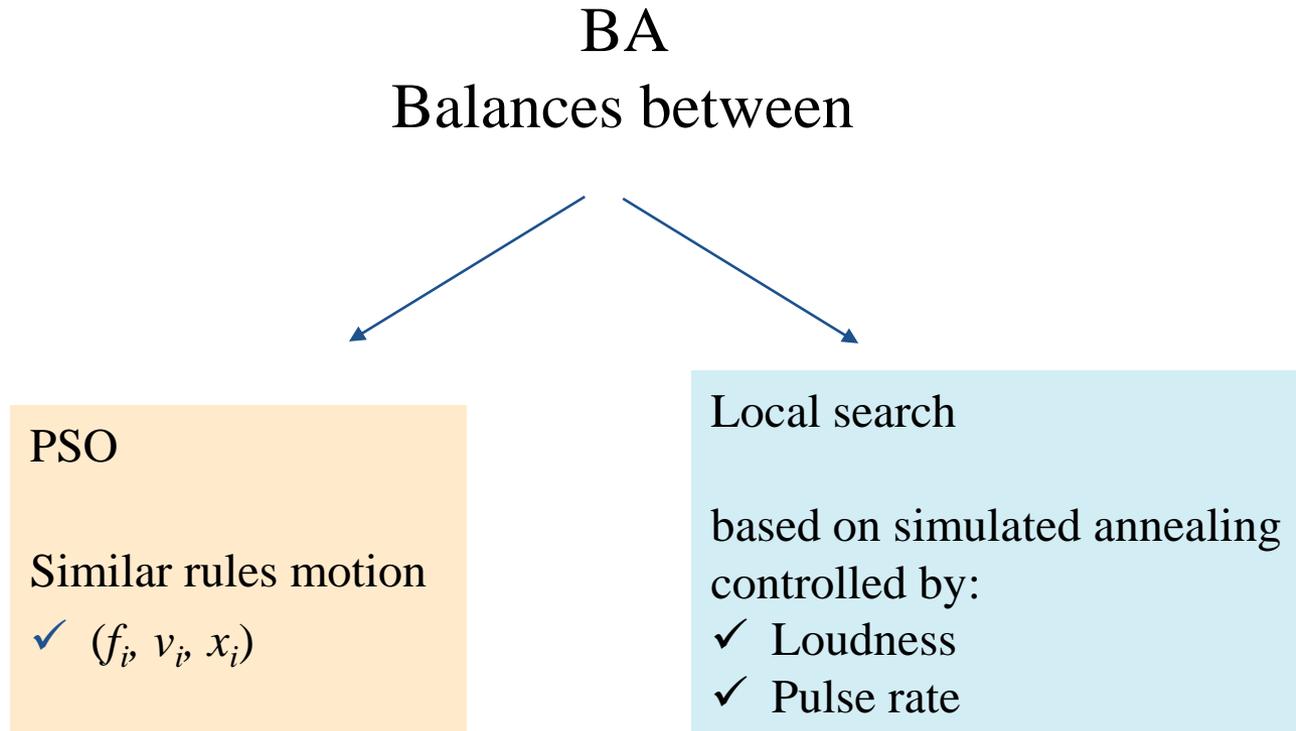


Parameters setting

- The parameters for BA are :
 - Maximum number of iterations.
 - Number of bats.
 - f_{min}
 - f_{max}
 - α
 - γ

Bat Algorithm: An extension of PSO

- BA can be seen as a hybridization of PSO and a local search.



Important Features

□ **BA is equivalent to PSO** when:

- f_i is a random number,
- $A_i = 0$
- $r_i = 1$

□ **BA is equivalent to Harmony Search** when:

- $A_i = r_i$

□ **BA is then more powerful than PSO and Harmony Search**

Some Variants of BA

□ FLBA: Fuzzy Logic Bat Algorithm

- Khan, K., Nikov, A., Sahai A., A Fuzzy Bat Clustering Method for Ergonomic Screening of Office Workplaces, S3T 2011, Advances in Intelligent and Soft Computing, 2011, Volume 101/2011, 59-66 (2011).

□ MOBA: Multi-Objective Bat Algorithm

- Yang, X. S., Bat algorithm for multi-objective optimization, Int. J. Bio-Inspired Computation, Vol. 3, No. 5, pp. 267–274, (2011).

□ BBA: Binary Bat Algorithm

- Nakamura, R. Y. M., Pereira, L. A. M., Costa, K. A., Rodrigues, D., Papa, J. P., Yang, X. S., (2012), BBA: A binary bat algorithm for feature selection, in: 25th SIBGRAPI Conference on Graphics, Patterns and Images (SIBGRAPI), 22-25 Aug. 2012, IEEE Publication, pp. 291-297.
- S. Mirjalili, S. M. Mirjalili, X. Yang, Binary Bat Algorithm, Neural Computing and Applications, 2014, Springer.

Some Variants of BA

□ EBA (Evolving Bat Algorithm)

- P. W. Tsai, J. S. Pan, B. Y. Liao, M. J. Tsai, V. Istanda, Bat algorithm inspired algorithm for solving numerical optimization problems, Applied Mechanics and Materials, Vo.. 148-149, pp.134-137 (2012)

□ IBA (Improved Bat Algorithm)

- Y. Selim and U. K. Ecir, "Improved Bat Algorithm (IBA) on Continuous Optimization Problems," Lecture Notes on Software Engineering, vol. 1, no. 3, pp. 279-283, 2013.

Applications

- ❑ Continuous Optimization
 - Non-linear problems
 - Mathematic Continuous Functions

- ❑ Combinatorial Optimization
 - Scheduling problems

- ❑ Data Mining
 - Clustering problems
 - Classification problems
 - Association Rules Mining

- ❑ Computer Vision
 - Image matching

A Case Study: Max-SAT

□ Definition

Let $V = \{v_1, v_2, \dots, v_n\}$ be a set of Boolean variables

- a **literal** is a Boolean variable that appears with or without the negation operator.
- a **clause** is a Boolean disjunction of literals.
- the problem SAT is defined by the following (instance, question) pair:

Instance: m clauses over n Boolean variables (a CNF Boolean formula)
Question: is there an instantiation or interpretation of variables for which all the clauses are true simultaneously?

□ Example

$V = \{v_1, v_2, v_3, v_4\}$, $C = \{c_1, c_2, c_3\}$ such that:

$$\begin{cases} c_1 = v_1 + v_2 + \overline{v_4} \\ c_2 = v_2 + \overline{v_3} + v_4 \\ c_3 = \overline{v_1} + \overline{v_2} + v_3 \end{cases}$$

Where bar sign denotes the negation operator and '+' the disjunctive operator. One possible solution is the instantiation $\{T, T, T, T\}$ respectively assigned to $\{v_1, v_2, v_3, v_4\}$.

Solving Max-SAT with BA

□ Solution coding

- a solution is a vector of n Boolean values, each one assigned to a variable.
- It is then a chain of n bits.

□ Search space

- the set of all potential instantiations for the instance.
- It is then the set of all Boolean vectors of length equal to n .
- its size is equal to 2^n .

□ Fitness function

- for Max-SAT
 - ✓ the number of satisfied clauses. The function is to be maximized or
 - ✓ the number of unsatisfied clauses. The function here is to be minimized.
- for Max-w-SAT
 - ✓ the sum of the weights of the satisfied clauses. The function is to be maximized or
 - ✓ the sum of the weights of the unsatisfied clauses. The function is to be minimized.
-

Distance between two solutions

□ **Hamming Distance** between two strings x and y of same length equal to n :

- it is equal to the number of entries with different symbols

- $distance(x, y) = \sum_{i=1}^{i=n} x_i \oplus y_i$

$$\text{where } x_i \oplus y_i = \begin{cases} 0 & \text{if } x_i = y_i \\ 1 & \text{otherwise} \end{cases}$$

- examples

- ✓ $x = \text{ababcaabda}$, $y = \text{acabbaaada}$, then $distance(x, y) = 3$

- ✓ $x = 0010101110$, $y = 0100100000$, then $distance(x, y) = 5$

□ **Similarity** between two strings x and y of equal length

- $Similarity(x, y) = n - distance(x, y)$

□ **Dissimilarity** between two strings x and y of equal length

- $Dissimilarity(x, y) = distance(x, y)$

□ **The degree of diversity.**

- The degree of diversity of a solution s relatively to a set S of other solutions is measured by the minimum of the distances between s and the elements in S .
- It is calculated as: $diversity(s) = \text{Min} \{ distance(s, t), t \in S \}$.

BA-SAT

```
begin  
  generate at random a population of  $n$  bats ( $n$  solutions);  
  for each bat  $i$  do  
    define its loudness  $A_i$ , its pulse frequency  $f_i$  and its velocity  $v_i$ ;  
    set its pulse rate to  $r_i$  ;  
    select the best solution  $x^*$ ;  
  while ((Max-Iter not reached) do  
    for each  $t = 1$  to  $n$  do  
      compute a new solution  $(f_i, v_i, x_i)$  using these formulas  
      if ( $\text{rand} > r_i$ ) then  
        select a solution  $x'$  among the best solutions;  
        improve the solution using the following formula ;  
      end if;  
      generate at random a new solution  $(f_i, v_i, x_i)$  ;  
      if ( $\text{rand} < A_i$ ) and ( $f(x_i) < f(x')$ ) then  
        accept the new solution; end if  
        increase  $r_i$  and reduce  $A_i$  using these formulas  
      end for  
    Rank the bats and find the current best  $x^*$  ;  
  end while  
end
```

In the initialization, consider a velocity as a distance, which is a non negative number.

$$f_i = f_{min} + (f_{max} - f_{min})\beta$$

$$v_i^t = \lfloor v_i^{t-1} + \text{distance}(x_i^t, x_*)f_i \rfloor$$

Invert v_i^t bits of x_i^{t-1} to obtain x_i^t

Perform a local search

$$A_i^t = \alpha A_i^{t-1}$$

$$r_i^{t+1} = r_i^0(1 - e^{\gamma t})$$

Experiments

Table 1: Comparison of BA with GA, and PSO.

Functions/Algorithms	GA	PSO	BA
Multiple peaks	52124 \pm 3277(98%)	3719 \pm 205(97%)	1152 \pm 245(100%)
Michalewicz's ($d=16$)	89325 \pm 7914(95%)	6922 \pm 537(98%)	4752 \pm 753(100%)
Rosenbrock's ($d=16$)	55723 \pm 8901(90%)	32756 \pm 5325(98%)	7923 \pm 3293(100%)
De Jong's ($d=256$)	25412 \pm 1237(100%)	17040 \pm 1123(100%)	5273 \pm 490(100%)
Schwefel's ($d=128$)	227329 \pm 7572(95%)	14522 \pm 1275(97%)	8929 \pm 729(99%)
Ackley's ($d=128$)	32720 \pm 3327(90%)	23407 \pm 4325(92%)	6933 \pm 2317(100%)
Rastrigin's	110523 \pm 5199(77%)	79491 \pm 3715(90%)	12573 \pm 3372(100%)
Easom's	19239 \pm 3307(92%)	17273 \pm 2929(90%)	7532 \pm 1702(99%)
Griewangk's	70925 \pm 7652(90%)	55970 \pm 4223(92%)	9792 \pm 4732(100%)
Shubert's (18 minima)	54077 \pm 4997(89%)	23992 \pm 3755(92%)	11925 \pm 4049(100%)

Xin-She Yang, *Nature Inspired Cooperative Strategies for Optimization (NISCO 2010)*, in Studies in Computational Intelligence, Springer Berlin, 284, Springer, 65-74 (2010)

Conclusions

□ Strength

- A promising algorithm for continuous optimization problems
 - ✓ Simulation of the original echolocation behavior of bats
 - A more sophisticated and structured process
 - ✓ Includes hybrid successful strategies of previous evolutionary algorithms such as:
 - Local search
 - Simulated annealing
 - PSO
 - ✓ Includes a random walk strategy
- Compared to other evolutionary algorithms, it has been shown to be more powerful than:
 - ✓ PSO
 - ✓ Genetic algorithm
 - ✓ Harmony search
- A good convergence
 - ✓ Thanks to the parameters α and γ that implement the convergence strategy inspired from the simulated annealing
- Numerous important variants:
 - ✓ MO-BAT, IBA, EBA, Fuzzy BA, ...

Limitations and Perspectives

□ Limitations

- More analyses for algorithm convergence.
- More comparisons with other functions and Problems with higher number of dimensions.

□ Perspectives

- More sophisticated modelling of pulse and loudness rates.
- More variants.
- More applications.

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Thank You !